



Editorial

Tasks, test data and solutions were prepared by: Fabijan Bošnjak, Nikola Dmitrović, Karlo Franić, Marin Kišić, Josip Klepec, Daniel Paleka, Ivan Paljak and Paula Vidas. Implementation examples are given in attached source code files.

Task: Pod starim krovovima

Suggested by: Nikola Dmitrović and Marin Kišić

Necessary skills: greedy algorithm

The solution is based on an idea that we should start filling the largest (in terms of volume) glass as much as possible. If we have filled the largest glass, we should move to the next one, and so on until there are no glasses left. In that way we will certainly end up with as much empty glasses as possible.

The time complexity of this greedy algorithm is $\mathcal{O}(N \log N)$ due to sort. Notice that the constraints were much lower in this task so that less efficient sorting algorithms or correct simulations get all points.

Task: Spiderman

Suggested by: Ivan Paljak

Necessary skills: math, complexity analysis

Let's solve the easier versions of the task first that were given in the *Scoring* section.

The first partial score worth a total of 14 points could have been solved by a simple simulation. In other words, we could have used two nested loops to fix each pair of skyscrapers and check whether Peter can jump from one to the other. The time complexity of this solution is $\mathcal{O}(N^2)$.

For additional 14 points you should have used the fact that there are mere 2000 different heights among all skyscrapers. We can store for each of these heights how many skyscrapers have it and now the task boils down to a solution very similar to the one described above. Instead of visiting each pair of skyscrapers, we will visit each pair of heights and store the solution for each height. The time complexity of this solution is $\mathcal{O}(M^2)$ where M represents the number of different heights among the skyscrapers.

In test cases worth additional 14 points, you could have assumed that $K = 0$. In other words, from skyscraper of height h_i it was possible to jump on a skyscraper of height h_j if h_j is a divisor of h_i . Finding all divisors of a certain number x can relatively easy be done in $\mathcal{O}(\sqrt{x})$. Therefore, we have an algorithm of time complexity $\mathcal{O}(N\sqrt{\max_H})$ which should score these 14 points. If you are not familiar with a popular algorithm that finds the all divisors of a given number, feel free to visit this [link](#).

Solving the entire problem could have been done via a slight modification of the previous algorithm (hint: observe all divisors of $h_i - k$), but here we will explain a slightly different and faster algorithm. Let's ask ourselves: „From which skyscrapers can we jump on a skyscraper that is h_i meters high?”. The answer is, naturally, from skyscrapers of height K or $K + h_i$ or $K + 2h_i$ or $K + 3h_i$ or Let \max_H denote the height of the highest possible skyscraper, then we can jump on skyscraper of height h_i from $\sim \frac{\max_H}{h_i}$ different heights. The question presents itself, can we traverse over all candidate heights for each skyscraper within the given time limit? Let's assume the worst case in which all heights of skyscrapers are different (otherwise we just use the same trick from second subtask). Therefore, the skyscrapers have heights $1, 2, \dots, \max_H$. For the first skyscraper we have $\sim \frac{\max_H}{1}$ candidates to traverse, for the second one we have $\sim \frac{\max_H}{2}$ candidates to traverse, ... and for the last one we have $\sim \frac{\max_H}{\max_H}$ candidates to traverse. Therefore, the total number of candidates to traverse is $\sim \max_H \lg \max_H$ which is small enough to pass all test cases. If you are struggling with the last observation, we suggest you familiarize yourself with the complexity analysis of a famous algorithm called *Sieve of Eratosthenes* or simply check out [this document](#).



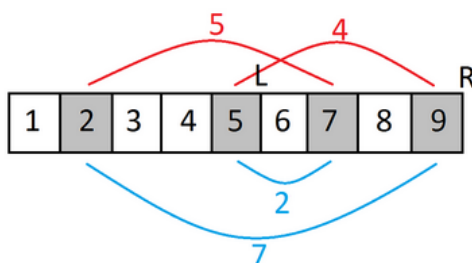
Task: Holding

Suggested by: Fabijan Bošnjak and Marin Kišić

Necessary skills: dynamic programming, memory optimizations

The solution of the first subtask is based on dynamic programming where the state is a bitmask. We leave the rest of the details as a practice to the reader.

In the second subtask it is known that $R = N$, which means that we can swap numbers on positions $L, L + 1, \dots, R$ only with numbers on positions from 1 to $L - 1$ (the rest of the solution assumes that the word *interval* refers to the agreed interval $L, L + 1, \dots, R$). The first important observation is that we will never change the position of a certain number more than once. The second important observation, and much less obvious than the first, is that we only care about which elements were chosen to be swapped within the interval and which were chosen to be swapped outside the interval. Regardless of the way in which we have swapped these numbers, their total cost will remain invariant. For example, if we decided to swap positions i and j from within the interval with positions k and l that are outside the interval, it doesn't matter whether we have changed i with k and j with l or i with l and j with k . We leave the formal proof of this claim as an exercise to the reader.



Now it is obvious that the only important thing left is to decide which elements should be chosen from inside and which elements should be chosen from outside of the interval and that the number of chosen elements from inside equals the number of chosen elements outside of interval. We can achieve that using *dp* whose arguments are the current position outside the interval, current position inside the interval and the total amount of money we have spent thus far. The *dp* function returns the maximum decrease in sum of elements in our interval. The initial state of *dp* is $dp(1, L, 0)$ and the state where we will find our solution is $dp(L - 1, R, K)$.

$$dp(poz_{out}, poz_{in}, spent) = \max \left\{ dp(poz_{out} - 1, poz_{in}, spent), dp(poz_{out}, poz_{in} - 1, spent), \right. \\ \left. dp(poz_{out} - 1, poz_{in} - 1, spent - (poz_{in} - poz_{out})) + A[poz_{in}] - A[poz_{out}] \right\} \quad (1)$$

The first *dp* transition tells us not to take an element on position poz_{out} , the second transition tells us not to take an element on position poz_{in} , while the third transition tells us to take both elements and swap them, thus spending $poz_{in} - poz_{out}$ kunas.

The complexity of this algorithm is $\mathcal{O}(N^2 \cdot K)$.

This algorithm is therefore fast enough for the whole solution, but doesn't include the swaps from the right side of the interval because $R = N$. Suppose that the optimal solution takes X elements left of the interval, Y elements right of the interval and $X + Y$ elements from inside the interval. It is obvious that, if we sort positions of elements we took from within the interval, first X elements will be swapped with the X chosen elements on the left side and next Y elements will be swapped with the Y chosen elements on the right side. This leads us to a conclusion that there is a line between positions within the interval which determines that all elements from the interval left of that line will be swapped with chosen elements



left of the interval, and vice versa for the right side. Since we don't know where that line might lie and since we don't actually care how many swaps are made on each side of an interval, we can place that line on each position within the interval. We can do that with the following lines of code:

```
for i in range (L - 1, R+1):  
    for j in range (0, K + 1):  
        sol = max(sol, dpL(L - 1, i, j) + dpR(R + 1, i + 1, K - j))
```

What are dpL and dpR ? dpL is the same dp from the last subtask and dpR is completely identical to it but is being done from the other side. The complexity of each dp is $\mathcal{O}(N^2 \cdot K)$ and the complexity of merging their solutions is $\mathcal{O}(N \cdot K)$. Therefore, the total complexity of the algorithm is $\mathcal{O}(N^2 \cdot K)$.

Why can't you score all the points with that solution then? Because tridimensional array of the form `int dp[N][N][K]` takes up too much memory for $N = 100$, but it fits for $N = 50$. Therefore, we still need to optimize our memory consumption. There are multiple ways to achieve that, but perhaps the easiest is to note that, in the worst case for any N , L and R , the maximum amount of money Ivica needs to perform all swaps is going to be bounded by $\frac{N^2}{4}$. Luckily, arrays of the form `int dp[N][N][N*N/4]` fit into the given memory limit of 256 MiB. There is another optimization which swaps the dimension N with a smaller constant, you can check the implementation of that optimization in the attached source code.

Task: Klasika

Suggested by: Ivan Paljak

Necessary skills: dfs tree traversal, trie

The first two subtasks were solvable by more or less efficient attempts to simulate the process described in the task statement. We will leave further analysis of those solutions as exercises to the reader.

In the third subtask you were supposed to answer each **Query** with the longest path in a tree which starts on given node a . Note that the definition of path length is a bit peculiar, i.e. instead of summing up the edge weights, we are asked to **xor** them. Let's denote the distance between nodes x and y with $d(x, y)$. Note that $d(x, y) = d(1, x) \text{ xor } d(1, y)$ holds for each pair of nodes. We can use this property and keep around the distance from the root to each of the nodes while executing the queries. Finding the greatest distance from a given node a now boils down to finding another value $d(1, b)$ from the set of remembered values which when **xor**-ed with $d(1, a)$ gives a maximal value. This is a well-known problem which can be easily solved using the *trie* data structure. If you are not familiar with the problem, we suggest you try to find the solution by yourself. If you don't succeed, check out [this link](#).

The solution which scores all points is conceptually very similar to the one described above. The only problem we are having is that, when we traverse the trie, we don't know whether that part of the trie holds any value that is related to a node that is in a subtree of node b . Imagine that we know the values **discovery** and **finish** for each node which represent the moments when a dfs traversal function enters and leaves that particular node. Suppose that in each trie node we store a set of discovery times of all tree nodes whose distances from the root live in that subtree of our trie. Then we could simply make sure never to enter a trie node that doesn't hold a value related to subtree of node b while processing the **Query**. More precisely, we can traverse a node in a trie if its set of discovery times contains a value that is greater or equal to **discovery[b]** and less or equal to **finish[b]**.

Turns out this is relatively easy to achieve. First we will apply all **Add** queries (offline) and use a single dfs traversal to find **discovery** and **finish** values for each node. Then we will traverse through all queries once more and perform the algorithm described above. When adding a new element to the trie, we will simply append the corresponding **discovery** value to each of the visited trie nodes. Finally, when answering a query we will make sure we don't visit trie nodes that don't contain values related to the subtree of node b .



Task: Nivelle

Suggested by: Daniel Paleka

Necessary skills: sliding window technique, two pointers

We can implement a solution of time complexity $\mathcal{O}(N^2)$ which for every substring calculates the number of different letters in it. If we use the so-called sliding window technique, we need to keep track how many times each letter appears and note each time when a new letter starts or stops appearing. For implementation details, check the attached (slower) source code.

Note that the numerator of the expression we want to minimize, i.e. the number of different characters in a substring, can either be 1, 2, ..., 26. Therefore, it is enough to fix its value in every possible way and determine the largest possible substring which has exactly that many different characters. Now we have 26 values to compare and pick the smallest one.

A simple implementation calculates for each starting character the longest substring which contains exactly K different characters. If we calculate for each character and each position the first next appearance of that character, for each starting character we can quickly check ≤ 26 strings which go to *the next new character*.